

Recap: Variational Analysis

$$\theta^* = \operatorname{argmin}_{\theta} f(\theta) \quad \Bigg| \quad \theta^*: f(\theta) = 0$$

$$\theta_n^* = \operatorname{argmin}_{\theta} f_n(\theta) \quad \Bigg| \quad \theta_n^*: f_n(\theta) = 0$$

Q. If $f \approx f_n$ in some sense, how far θ and θ^* can be?
Can we quantify the proximity btw θ and θ^* ?

Ex 1: LSE. $f(\theta) = \mathbb{E}(Y - X^T \theta)^2$ $f_n(\theta) = \frac{1}{n} \sum_{i=1}^n (Y_i - X_i^T \theta)^2$

Ex 2: Minimization w/o constraints.

$$\theta^* = \operatorname{argmin}_{\theta} \mathbb{E} \ell(X, \theta) \quad \theta_n^* = \operatorname{argmin}_{\theta} \frac{1}{n} \sum_{i=1}^n \ell(X_i, \theta)$$

(Hjort and Pollard, 2011) If $\ell(X, \cdot)$ is convex then

$$|\theta^* - \theta_n^*| \leq \varepsilon \quad \text{whenever}$$

Ex 3. $\theta^* = \operatorname{argmin}_{\theta} f(\theta) \quad \theta_n^* = \operatorname{argmin}_{\theta} f(\theta_0) + (\theta - \theta_0)^T \nabla f(\theta_0)$

Kantorovich's theorem. Under some smoothness $+\frac{1}{2}(\theta - \theta_0)^T \nabla^2 f(\theta_0)(\theta - \theta_0)$

$$\|\theta^* - \theta_n^*\|_2 \lesssim \|\nabla^2 f(\theta_0)^{-1} \cdot \nabla f(\theta_0)\|_2^2$$

Def. Epi-convergence. For a seq. of ^{i.s.c.} fns $\{f_n: \mathcal{X} \rightarrow \mathbb{R}\}$ and a fn $f: \mathcal{X} \rightarrow \mathbb{R}$
 $f_n \xrightarrow{e} f$ if $\forall x \in \mathcal{X}$

① $\forall x_n \rightarrow x \quad \liminf f_n(x_n) \geq f(x)$

② $\exists x_n \rightarrow x \quad \limsup f_n(x_n) \leq f(x)$

Remark 1. $\theta^* = \underset{\theta \in C}{\operatorname{argmin}} f(\theta) = \underset{\theta \in C}{\operatorname{argmin}} f(\theta) + f_C(\theta)$.

$$f_C(\theta) = \begin{cases} 0 & \theta \in C \\ \infty & \theta \notin C \end{cases} \quad \left| \quad \theta^* \text{ activates } C. \right.$$

Remark 2. We may consider $(X, \|\cdot\|)$ or $(\mathbb{R}^d, \|\cdot\|)$

Thm 3.10 of Attouch and Wets (1983)

Let $x_n \in \operatorname{argmin} f_n(x)$, $x_n \rightarrow x$, and $f_n \xrightarrow{e} f$ then

$$x \in \operatorname{argmin} f(x).$$

pf. $\forall y \in X \quad \exists y_n \rightarrow y$ s.t. $\limsup_n f_n(y_n) \leq f(y)$

$$f(x) \leq \liminf_n f_n(x_n) \leq \liminf_n f_n(y_n) \leq \limsup_n f_n(y_n) \leq f(y)$$

Epi-convergence $\Rightarrow$ minimizers converge.

1. Stronger result is possible.

2. whether $\exists \mathcal{I}$ on lsc-fun(X) s.t. $\mathcal{I}(f_n, f) \rightarrow 0 \Rightarrow f_n \xrightarrow{e} f$

whether $\exists F$ s.t. $d(x_n, x) \leq F(\mathcal{I}(f_n, f))$

Painleve - Kuratowski convergence. (PK-convergence)

Def. Painleve - Kuratowski (PK) convergence of sets $\{A_n \in \mathcal{A}\}$.

$$\limsup_n A_n = \{x \in \mathcal{A} : \liminf_n d(x, A_n) = 0\}$$
$$= \{x \in \mathcal{A} : \exists \{x_{n_k} \in A_{n_k}\} \text{ s.t. } x_{n_k} \rightarrow x\}$$

$$\liminf_n A_n = \{x \in \mathcal{A} : \limsup_n d(x, A_n) = 0\}$$
$$= \{x \in \mathcal{A} : \exists \{x_n \in A_n\} \text{ s.t. } x_n \rightarrow x\}.$$

$$PK\text{-}\lim A_n = \limsup_n A_n \stackrel{\textcircled{1}}{=} \liminf_n A_n \text{ if } \textcircled{1} \text{ hold}$$

① For a seq of closed constraints $\{C_n\}$

$$\delta_{C_n} \xrightarrow{\text{epi}} \delta_C \iff PK\text{-}\lim C_n = C.$$

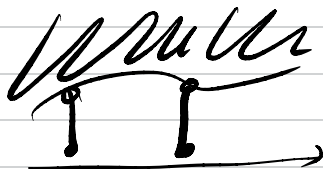
②

Def. Epi-graph. For a lsc ftn f define

$$\text{epi-}f = \{(x, \alpha) \in \mathcal{A} \times \mathbb{R} : f(x) \leq \alpha\}$$

$$f_n \xrightarrow{e} f \text{ iff}$$

$$PK\text{-}\lim \text{epi-}f_n = \text{epi-}f.$$



Useful in quantifying a distance btw f_n &

$$\mathcal{J}(f_n, f) = \text{Haus}(\text{epi-}f_n, \text{epi-}f)$$

Thm 3.9 of Rockafeller and Wets (2018)

$$\forall \varepsilon_n \downarrow 0 \quad \limsup_n \varepsilon_n - \arg\min f_n \subseteq \arg\min f$$

$$\varepsilon_n - \arg\min f_n = \{ \theta : f_n(\theta) \leq \inf f_n(\theta) + \varepsilon_n \}$$

Application 1. Unconstrained M estimation

$$\theta^* = \arg\min M(\theta) = \arg\min \mathbb{E} \ell(X, \theta)$$

$$\hat{\theta}_n \in \arg\min \hat{M}_n(\theta) = \arg\min \frac{1}{n} \sum_{i=1}^n \ell(X_i, \theta)$$

If $\hat{M}_n(\theta) \xrightarrow{p} M(\theta)$ a.s., then $\forall \varepsilon_n \downarrow 0$ a.s.

$$\limsup_n \underbrace{\{ \theta : \hat{M}_n(\theta) \leq \hat{M}_n(\hat{\theta}_n) + \varepsilon_n \}}_{\hat{C}_n} \subseteq \{ \theta_0 \}$$

① $\varepsilon_n = 0 \rightarrow$ as. convergence of M-estimator.

② If $\hat{C}_n$ is an (asymptotically) valid confidence set for θ_0 ,
 $\text{Diam}(\hat{C}_n) \rightarrow 0$. (Takatsu and Kuchibhotla 2025+)

Set convergence in set^*

Section 7 Royset (2020), Rockafeller and Royset (2014), Assouli (2018)

Application 2. Constrained M-estimation.

$$\hat{\theta}_n = \underset{\theta \in \Theta_n}{\operatorname{argmin}} \hat{M}_n(\theta) = \underset{\theta \in \Theta_n}{\operatorname{argmin}} \hat{M}_n(\theta) + f_{\Theta_n}(\theta)$$

$$\begin{aligned} r_n(\hat{\theta}_n - \theta_0) &= \underset{u}{\operatorname{argmin}} S_n \left\{ \hat{M}_n \left(\theta_0 + \frac{u}{r_n} \right) - \hat{M}_n(\theta_0) \right\} \\ &\quad + f_{\Theta_n} \left(\theta_0 + \frac{u}{r_n} \right) - f_{r_n(\Theta_n - \theta_0)}(u) \\ &= \underset{u}{\operatorname{argmin}} S_n \left\{ (\hat{M}_n - M) \left(\theta_0 + \frac{u}{r_n} \right) - (\hat{M}_n - M)(\theta_0) \right\} \xrightarrow{e} S(u) \\ &\quad + S_n \left\{ M \left(\theta_0 + \frac{u}{r_n} \right) - M(\theta_0) \right\} \xrightarrow{e} D(u) \\ &\quad + f_{r_n(\Theta_n - \theta_0)}(u) \xrightarrow{e} f_c(u). \end{aligned}$$

Pollard 1984 Brownian Motion.

Then, $r_n(\hat{\theta}_n - \theta_0) \xrightarrow{d} \underset{u}{\operatorname{argmin}} S(u) + D(u) + f_c(u)$

$$\textcircled{1} \quad f_n \xrightarrow{e} f \quad \text{and} \quad g_n \xrightarrow{e} g \Rightarrow f_n + g_n \xrightarrow{e} f + g \quad \textcircled{*}$$

$\textcircled{*}$ is not true in general.

Prop 3.4 of Roysset (2020)

If either of the following holds, then $\textcircled{*}$ holds.

$$\textcircled{1} \quad -f_n \xrightarrow{e} -f \quad \text{or} \quad -g_n \xrightarrow{e} -g.$$

$$\textcircled{2} \quad f_n \rightarrow f \quad \text{and} \quad g_n \rightarrow g \quad \text{pointwise.}$$

$$① \Leftrightarrow \lim_n f_n(x_n) = f(x) \quad \forall x_n \rightarrow x.$$

② For a stochastic process. Skorokhod representation
 a.s. convergence $\Leftrightarrow$ convergence in dist.

a.s. epi-convergence $\Leftrightarrow$ epi-convergence in dist.

(A.s. representations for stochastic Process.

Thm 2.3 of Kim and Pollard, Thm 1.10.4 of Van der Vaart and Wellner.

For a stochastic process $\{f_n\}$ defined on $\mathbb{R}^d$

$$① (f_n(t_1), \dots, f_n(t_m))^T \xrightarrow{d} g(t_1, \dots, t_m)$$

② $\{f_n\}$ is uniformly tight.

Then $\exists$ prob space on where $\exists \tilde{f}_n, \tilde{f}$ s.t.

$$f_n \stackrel{d}{=} \tilde{f}_n, (\tilde{f}(t_1), \dots, \tilde{f}(t_m)) \stackrel{d}{=} g(t_1, \dots, t_m) \text{ and}$$

$$\sup_{u \in K} |\tilde{f}_n(u) - \tilde{f}(u)| \rightarrow 0 \quad \text{a.s.}$$

Thm 1 of Knight (1999).

If $Z_n \xrightarrow{e-d} Z$, $\varepsilon_n \xrightarrow{p} 0$, $U_n \in \varepsilon_n$ -argmin Z_n , and $U_n = O_p(1)$

then $U_n \xrightarrow{d} U = \text{argmin } Z$.

Tangent cones. One can verify they are ^{closed} cones

Contingent cone. $T_C^c(u) = \limsup_{\tau \downarrow 0} \frac{C - u}{\tau} = \{v : \liminf_{\tau \downarrow 0} \frac{d(u + \tau v, C)}{\tau} = 0\}$

Adjacent cone $\tilde{T}_C(u) = \{v : \limsup_{\tau \downarrow 0} \frac{d(u + \tau v, C)}{\tau} = 0\}$

Clarke cone $T_C^\dagger(u) = \{v : \limsup_{\substack{\tau \downarrow 0 \\ u' \rightarrow u}} \frac{d(u' + \tau v, C)}{\tau} = 0\}$

$T_C^\dagger(u) \subseteq \tilde{T}_C(u) \subseteq T_C^c(u)$ $u \in C^0$ then they are ^{convex} $\mathbb{R}^d$.

If C is closed and convex, then, they are all
(Clarke, 1983) same

C is Chernoff regular at u if $T_C(u) = T_C^\dagger(u)$

(Chernoff 1954, Geyer 1984) is used for asymptotic
for global minimizer.
(Geyer 1984)

C is Clarke regular at u if $T_C^\dagger(u) = T_C(u)$

(Geyer 1984) claimed if Clarke regular at true parameter

one can ^{local} ^{identify} ^{asym. disc. of} minimizer. ; they are asym. equivalent.

(Shapiro, 2000) This is not true, stronger assump. for

Application. Constraint ^{mean}-estimation.

$$\begin{aligned} \text{Ex. } \hat{\theta}_n &= \underset{\theta \in \Theta}{\operatorname{argmin}} \frac{1}{n} \sum \|x_i - \theta\|^2 = \underset{\theta \in \Theta}{\operatorname{argmin}} \|\bar{x}_n - \theta\|^2 \\ &= \operatorname{Proj}_{\Theta}(\bar{x}_n) \end{aligned}$$

$$\|\operatorname{Proj}_{\Theta}(\bar{x}_n) - \underbrace{\theta_0}_{\theta_0}\| \leq \|\bar{x}_n - \mu\| \xrightarrow{\text{a.s.}} 0$$

$$\ln(\hat{\theta}_n - \theta) = \underset{u}{\operatorname{argmin}} \frac{1}{n} \|\bar{x}_n - \theta_0 - \frac{u}{n}\|^2$$

$$= \underset{u}{\operatorname{argmin}} \frac{1}{n} \|\bar{x}_n - \theta_0\|^2 + \frac{1}{n} \|u\|^2 + \frac{2}{n} (\bar{x}_n - \theta_0)^T u$$

$$\Rightarrow \underset{u}{\operatorname{argmin}} \frac{1}{n} \|\bar{x}_n - \theta_0\|^2 + \frac{1}{n} \|u\|^2 + \frac{2}{n} (\bar{x}_n - \theta_0)^T u = \underset{z}{\operatorname{argmin}} f_n(\theta - \theta_0)(u)$$

$$\Theta = [0, 1] \rightarrow T_C(x) = (R \quad \forall x \in (0, 1))$$

$$T_C(0) = [0, \infty)$$

$$T_C(1) = (-\infty, 0] \rightarrow \max\{z, 0\}$$

$$\min\{z, 0\}$$